

1

$$V_d = 14V$$

$$V_o = 42V$$

$$P_o = 21W$$

$$f_s = 200kHz$$

$$\Delta i_L = 1.8A$$

$$T_s = \frac{1}{f_s} = \frac{1}{200kHz} = 5\mu s$$

$$V_o = V_d \left( \frac{D}{1-D} \right)$$

$$342 = 14 \cdot \left( \frac{D}{1-D} \right)$$

~~$$342 = 14 \cdot \left( \frac{D}{1-D} \right)$$~~

$$42 - 14D = 14D$$

~~$$D = 0.125$$~~

$$D = 0.75$$

$$DT = \text{~~1.25~~} 3.75\mu s$$

i)

$$\Delta i_L = \frac{V_d \cdot DT}{L}$$

$$L = \frac{14 \times 3.75\mu}{1.8}$$

$$L = 29.17\mu H$$

$$V_{D(on)} = V_d + V_o$$

$$V_{D(on)} = 56V$$

$$V_{D(off)} = 0$$

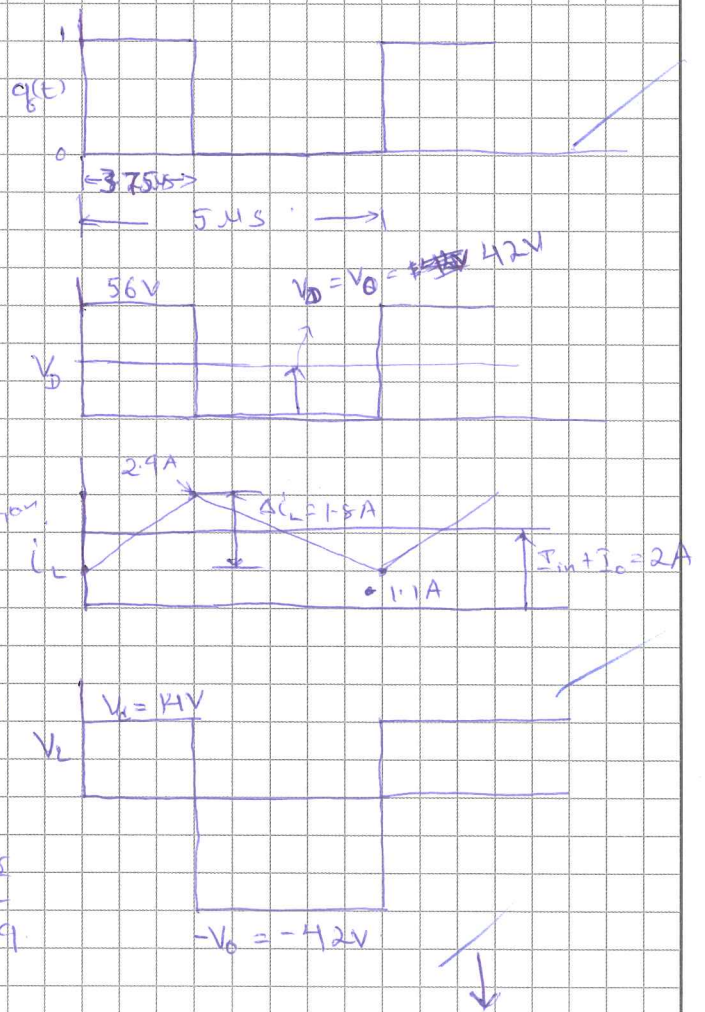
$$i_{L(max)} = I_L + \frac{\Delta i_L}{2}$$

$$i_{L(min)} = I_L - \frac{\Delta i_L}{2}$$

$$I_L = I_{in} + I_o$$

$$I_L = \frac{P_o}{V_{in}} + \frac{P_o}{V_o} = 2A$$

As per question order





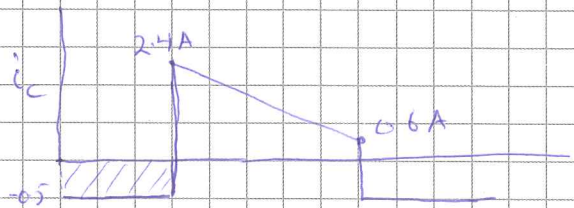
$$V_{L\text{on}} = V_d = 14\text{V}$$

$$V_{L\text{off}} = -V_o = -42\text{V}$$

$$i_{D\text{on}} = 0$$

$$i_{D\text{off}} = I_L$$

$$I_D = I_o = \frac{P_o}{V_o} = \frac{21}{42} = 0.5\text{A}$$



$$-i_C = I_D = I_o$$

$$(ii) \quad I_C = \frac{\Delta i_L}{2}$$

$$I_L = I_o + I_{in} \quad \Delta i_L = \frac{V_{in} D T}{2L}$$

$$\frac{P_{\text{caut}}}{V_o} + \frac{P_{\text{caut}}}{V_{in}} = \frac{V_{in} D T}{2L}$$

$$\frac{P_{\text{caut}}}{42} + \frac{P_{\text{caut}}}{14} = \frac{14 \cdot 375 \mu}{2 \times 29.17 \mu}$$

$$9.5 \times 10^{-2} P_{\text{caut}} = 0.899$$

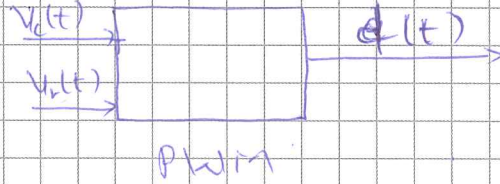
$P_{\text{caut}}$

$$P_{\text{caut}} = 9.43\text{W}$$

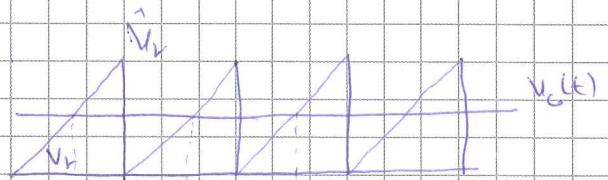


2

2.1

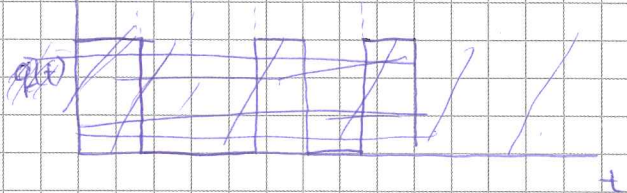


$$T_s = \frac{1}{f_s}$$

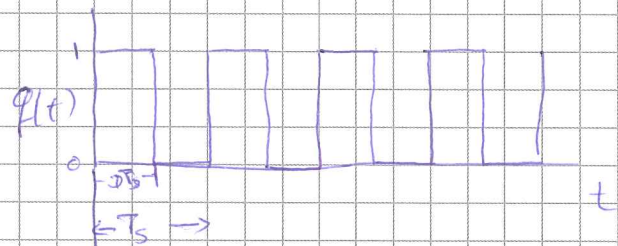


When  $V_c(t) > V_r \Rightarrow q(t) = 1$

When  $V_c(t) < V_r \Rightarrow q(t) = 0$



$$d(t) = \frac{V_c(t)}{V_r}$$



Linearizing around around DC steady state adding small disturbance

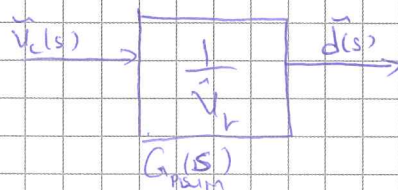
$$d(t) = D + \tilde{d}(t)$$

$$\tilde{V}_c(t) = V_c + \tilde{V}_c(t)$$

$$d(t) = \frac{V_c}{V_r} + \frac{\tilde{V}_c(t)}{V_r}$$

$\underbrace{\hspace{2cm}}_D \quad \underbrace{\hspace{2cm}}_{\tilde{d}(t)}$

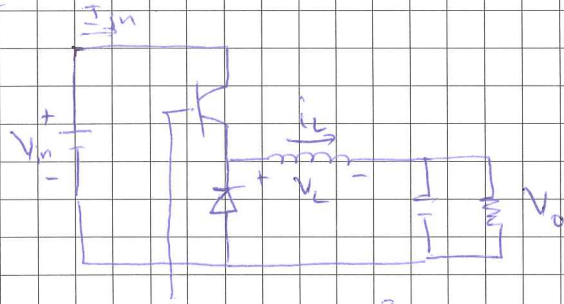
Taking transfer function of the small perturbation



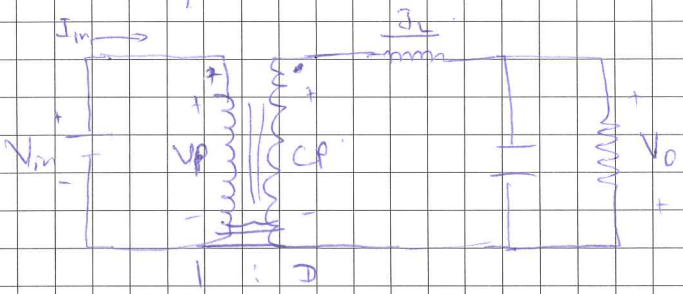
$$G_{\text{PWM}}(s) = \frac{\tilde{d}(s)}{\tilde{V}_c(s)} = \frac{1}{V_r}$$



2.2



Buck Converter



Average model representation of Buck Converter

From simplified <sup>steady state</sup> buck converter output voltage is given as

$V_o = V_{in} D$  --- (i)

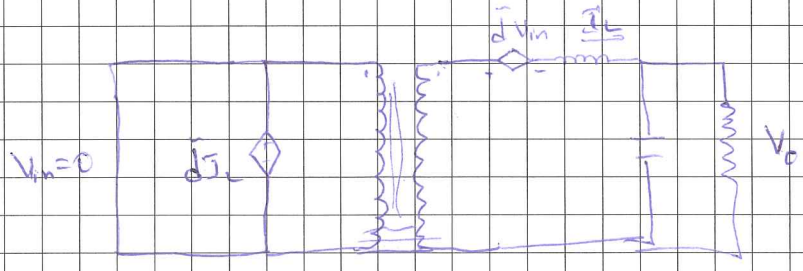
Current is given by

$I_{in} = I_o D$  --- (ii)

(X)

from page 5

for small perturbation a single pole representation of buck converter.





2.2 Taking Voltage: Component of average model

$$V_{cp} + \tilde{V}_{cp}(t) = (D + \tilde{d}(t)) (V_{vp} + \tilde{V}_{vp}(t))$$

neglected

$$\tilde{V}_{cp} + \tilde{V}_{cp}(t) = \cancel{D V_{vp}} + \tilde{d}(t) V_{vp} + D \tilde{V}_{vp}(t) + \cancel{\tilde{d}(t) \tilde{V}_{vp}(t)}$$

$$\tilde{V}_{cp}(t) = \tilde{d}(t) V_{vp} + D \tilde{V}_{vp}(t) \quad \dots (1)$$

Taking current

$$I_{vp} + \tilde{I}_{vp}(t) = (D + \tilde{d}(t)) (I_{cp} + \tilde{I}_{cp}(t))$$

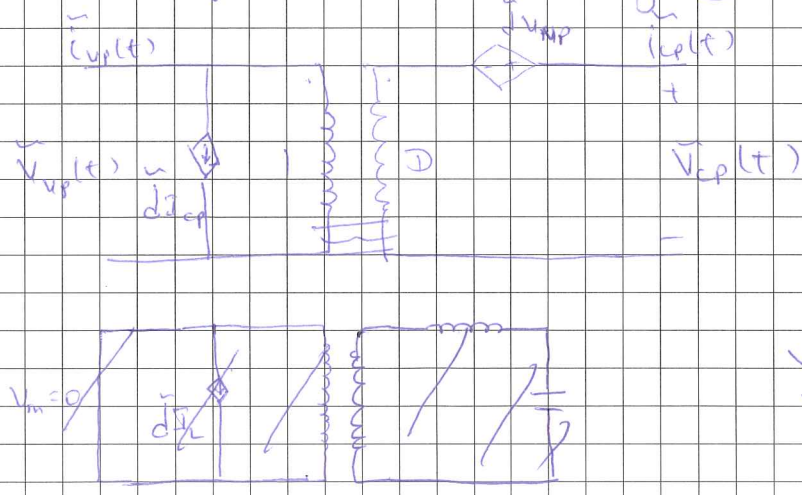
neglected

$$\tilde{I}_{vp} + \tilde{I}_{vp}(t) = \cancel{D I_{cp}} + I_{cp} \tilde{d}(t) + \cancel{D \tilde{I}_{cp}(t)} + \tilde{d}(t) \tilde{I}_{cp}(t)$$

$$\tilde{I}_{vp} = D I_{cp}$$

$$\tilde{I}_{vp}(t) = I_{cp} \tilde{d}(t) + \tilde{I}_{cp}(t) \tilde{d}(t) \quad \dots (2)$$

Taking Fig 3 & eq 1 & 2 are derived for small perturbation signals by using eq 1 & 2 small signal around a steady state operating point given by  $D, V_{vp}, I_{cp}$  can be represented as Fig 4



please see \*  
↓ Page 4



3.

3.1

$$V_s = 120V (\text{rms})$$

$$P = 0.95 \text{ kW}$$

$$I_{s1} = 10A (\text{rms})$$

$$\text{THD} = 75\%$$

a)  $\text{DPF} = ?$

$$P = V_s I_{s1} \cos \phi_1$$

$$\cos \phi_1 = \text{DPF}$$

$$\text{DPF} = \frac{950}{120 \times 10}$$

$$\underline{\text{DPF} = 0.79}$$

b)

$$I_{\text{distortion}} = ?$$

$$\% \text{THD} = \frac{I_{\text{dist}}}{I_{s1}} \times 100$$

$$I_{\text{distortion}} = \frac{75\% \times 10}{100}$$

$$\underline{I_{\text{dist}} = 7.5A (\text{rms})}$$

c)  $\text{PF} = ?$

$$\text{PF} = \frac{1}{\sqrt{1 + \left(\frac{\% \text{THD}}{100}\right)^2}} \cdot \text{DPF}$$

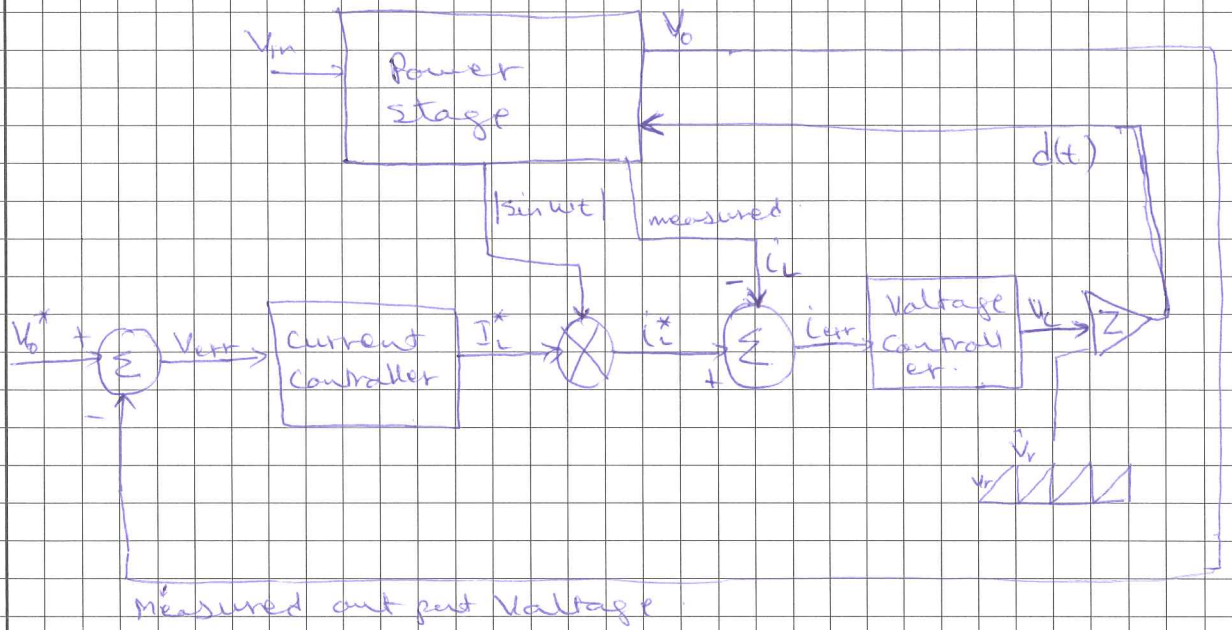
$$\text{PF} = \frac{1}{\sqrt{1 + \left(\frac{75}{100}\right)^2}} \cdot 0.79$$

$$\underline{\text{PF} = 0.632}$$

The power factor is below the acceptable limit, the limit is 0.707, so there must be some power factor correction done.



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- Measured output voltage compared with reference voltage
- The error voltage feed to Current Controller & Current Controller gives out amplitude of inductor current (reference)
- To the reference amplitude of the current ( $I_i^*$ ) Sinusoidal wave is multiplied from the circuit Sin wave
- The reference Sin wave ( $i_i^*$ ) compared with measured actual inductor current & the error feeds to Voltage Controller; the Voltage Controller gives out Control Voltage ( $V_c$ )
- Using PWM,  $V_c$  with  $V_r$  forms a switching pattern of  $d(t)$
- \* Current controller is fast responding relative to Voltage controller.



A

4.1

$$V_{in} = 120V(\text{rms})$$

$$f = 60\text{Hz}$$

$$T = \frac{1}{f} = \underline{16\text{ms}}$$

$$V_o = 250V$$

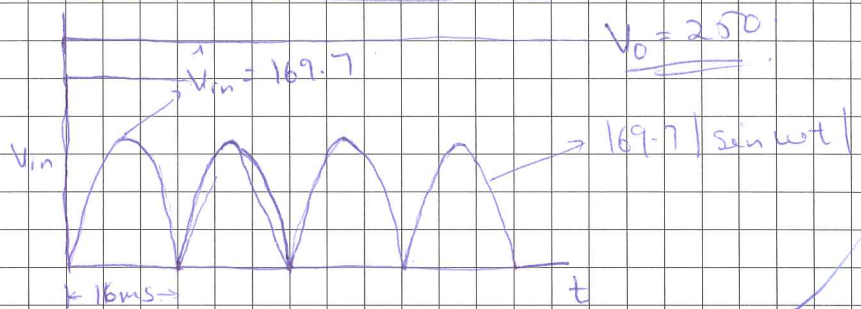
$$P_o = 250W$$

$$V_{in}(t) = \hat{V}_{in} |\sin \omega t|$$

$$\hat{V}_{in} = V_{in}(\text{rms}) \cdot \sqrt{2}$$

$$\hat{V}_{in} = 169.7$$

$$V_{in}(t) = 169.7 |\sin \omega t|$$



B

$$i_2(t) = i_{in}(t) = \hat{I}_{in} |\sin \omega t|$$

$$\hat{I}_{in} = \sqrt{2} \cdot I_{in}(\text{rms})$$

$$I_{in} = \frac{P_o}{V_{in}} = \frac{250}{120} = 2.08A(\text{rms})$$

$$\hat{I}_{in} = \sqrt{2} \cdot 2.08A(\text{rms})$$

$$\hat{I}_{in} = \underline{2.95A}$$

$$i_2(t) = 2.95 |\sin \omega t|$$







\*  $d(t)$  ?

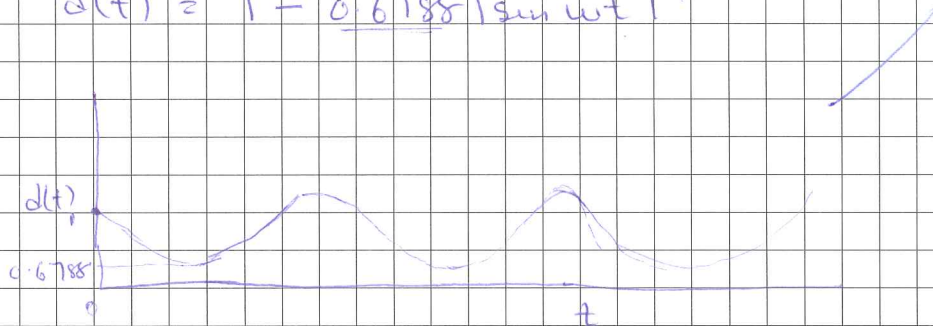
$$V_o = \hat{V}_{in} |\sin \omega t| \cdot \frac{1}{1-d(t)}$$

$$1-d(t) = \frac{\hat{V}_{in} |\sin \omega t|}{V_o}$$

$$d(t) = 1 - \frac{\hat{V}_{in} |\sin \omega t|}{V_o}$$

$$d(t) = 1 - \frac{169.7}{250} |\sin \omega t|$$

$$d(t) = 1 - 0.6788 |\sin \omega t|$$



\*  $P_{in} = P_o$

$$\hat{I}_{in} |\sin \omega t| \cdot \hat{V}_{in} |\sin \omega t| = V_o \cdot \hat{I}_d$$

current through diode  $\hat{I}_d = \frac{\hat{V}_{in} \hat{I}_{in} |\sin \omega t|^2}{V_o}$

$$2 \sin^2 \theta = 1 - \cos 2\theta$$

$$\hat{I}_d = \frac{\hat{V}_{in} \hat{I}_{in}}{2V_o} - \frac{\hat{V}_{in} \hat{I}_{in}}{2V_o} \cos(2\omega t)$$

→ let us assume the second harmonic current fully passes through capacitor

current through the load is  $\hat{I}_o$

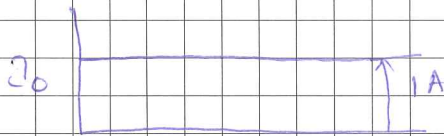
$$\hat{I}_o = \frac{\hat{V}_{in} \hat{I}_{in}}{2V_o}$$





$$I_0 = \frac{169.7 \times 2.95}{2 \times 250}$$

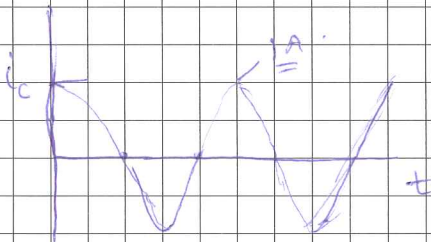
$$\underline{I_0 = 1A}$$



⊗  $i_c = ?$

$$i_c = \frac{\sqrt{2} I_0 \sin(\omega t)}{2V_0} \cos(\omega t)$$

$$\underline{i_c = 1 \cos 2\omega t}$$





4.2

$$\Delta V = \frac{I}{2\omega C} \cdot \hat{I}_d$$

$$\Delta V = \frac{1}{2\omega C} \cdot \frac{1}{2} \cdot \frac{\hat{V}_{in}}{V_0} \cdot \hat{I}_L \cdot \cancel{\cos 2\omega t}$$

$$\Delta V = \frac{1}{2\pi f C} \cdot \frac{1}{2} \cdot \frac{\hat{V}_{in}}{V_0} \cdot \hat{I}_L \quad \hat{I}_L = \hat{I}_{in}$$

$\omega = 2\pi f$

$$\Delta V = \frac{1}{4\pi \cdot 60 \times 220 \mu\text{F}} \cdot \frac{169.7}{250} \cdot 2 \cdot 95$$

$\Delta V = 12 \text{ V}$